

Energy Efficiency and Availability Improvement in Control and Operation of Superconducting Cavities

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- Energy Efficiency and Availability in Accelerator
- Challenges to Achieve Higher Efficiency and Availability
- Advanced Technologies makes it possible
- Some consideration/progress at ESS

Efficiency SRF Cavity at SNS(Sang-ho Kim)







Distinguish in two aspects:

- Enhance reliability in design and development stage(careful design, redundancy, high reliable key components, flexibility)
- Fault tolerance in operation stage: a mitigation strategy to the failures

Future Large Scale Accelerators (Erk Jensen, CWRF2016)



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FCC ee: CW, 0.8 GHz, P_{RF} total= 110 MW CLIC e+e-: Pulsed, 1.0 GHz, P_{RF} total= 180 MW

To Achieve Higher Efficiency and Availability



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Break through operation limitations:

- to work at nonlinearities
- to work close to limitation
- to change operation point quickly and correctly.

The Challenges



• System is usually optimized at designed operating point, while

• RF dynamics and cavity dynamics were/are often black box

- Cavity pass band modes
- Lorentz force detuning at different cavity field levels
- Lorentz force to cavity tuning transfer function
- Piezo tuner to cavity tuning transfer function (time domain, or frequency domain)
- Moto tuner to cavity tuning transfer function
- Microphonics spectrum
- System open loop matrix
- System closed loop matrix
- Cavity field behaviour close to and at quench
- Multipacting in cavity and power coupler
- Fast fault detection and fault recovery
- Power amplifier input-output characteristics (power and phase) at different modulator voltage
- Modulator ripple frequency and amplitude
- Circulator characteristics (return loss, frequency) under different power consumption, different reflection power, and working temperature
- Power amplifier bandwidth variation at different output power level
- Driver amplifier and power amplifier delay, rise time and falling time under different power level
- Phase drift in cables due to temperature or humidity changes

Insight into RF & Cavity Dynamics

- Rely heavily on high precision and online diagnostic of basic cavity parameters:
 - Cavity voltage
 - Synchronous phase
 - **QI** $\dot{\mathbf{V}}(t) = (-\omega_{1/2} + i\Delta\omega(t))\mathbf{V}(t) + \kappa_g \mathbf{I}_{\mathbf{g}}(t) + \kappa_b \mathbf{I}_{\mathbf{b}}(t)$
 - Detuning
 - R/Q
- Rely heavily on high precision and online diagnostic of critical parameters in RF power chain

Advanced Technologies Makes It Possible (Anders Johansson)

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The Goal at ESS





Operation Point of Typial Power Amplifier (e.x., Klystron)

The Last Thing to Overcome



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Online beam phase measurement



Phase Scan vs. Transient Beam Loading

• Phase Scan



• Transient Beam Loading





Phase Scan vs. Transient Beam Loading

| Accuracy and parameter used | Phase scan – signature matching | Transient beam loading – drift beam |
|-----------------------------------|---------------------------------------|---|
| Amplitude | ±2.4% | ±4% |
| Phase | ±1° | ±1° |
| Pulse length | <20µs | ≥50µs |
| Beam current | <20mA | <20mA |
| Rep. rates | 1Hz | 1Hz |

Improved Transient Beam Loading Method at DESY

• Rather than suffering from poor signal to noise ratio (SNR in some case <10dB), strong signal and clear information is observed



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Online Beam Phase Measurement



Online Beam Phase Measurement



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 $\dot{\mathbf{V}}(t) = (-\omega_{1/2} + i\Delta\omega(t))\mathbf{V}(t) + \kappa_g \mathbf{I}_{\mathbf{g}}(t) + \kappa_b \mathbf{I}_{\mathbf{b}}(t)$ and let the measured terms in the time derivative of $\mathbf{V}_{\mathbf{m}}$ form

the regressor matrix,

$$\mathbf{X} = \begin{bmatrix} \mathbf{V}_{\mathrm{m}}(t_1) & t_1 \mathbf{V}_{\mathrm{m}}(t_1) & \mathbf{\check{I}}_{\mathrm{g}}(t_1) & \Gamma(t_1) \\ \mathbf{V}_{\mathrm{m}}(t_2) & t_2 \mathbf{V}_{\mathrm{m}}(t_2) & \mathbf{\check{I}}_{\mathrm{g}}(t_2) & \Gamma(t_2) \\ \vdots & \vdots & \vdots \\ \mathbf{V}_{\mathrm{m}}(t_N) & t_N \mathbf{V}_{\mathrm{m}}(t_N) & \mathbf{\check{I}}_{\mathrm{g}}(t_N) & \Gamma(t_N) \end{bmatrix}$$

where

$$\Gamma(t_k) = \begin{cases} 0 & t_k \text{ before beam start} \\ 1 & t_k \text{ after beam start} \end{cases}.$$

Then the relation

$$\mathbf{y} = \mathbf{X}\boldsymbol{\theta}$$

is approximately satisfied for some parameter vector

$$\boldsymbol{\theta} = \begin{bmatrix} \boldsymbol{\theta}_1 & \boldsymbol{\theta}_2 & \boldsymbol{\theta}_3 & \boldsymbol{\theta}_4 \end{bmatrix}^T,$$

where $\angle \theta_4$ is the beam phase that we are looking for. The least squares estimate of θ is given by

$$\boldsymbol{\theta}_{\mathrm{LS}} = (\mathbf{X}^* \mathbf{X})^{-1} \mathbf{X}^* \mathbf{y}$$

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Opportunities and Challenges

• Build upon Existing High precision and online RF measurement: QI, detuning, klystron, circulator characteristics, etc..

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Opportunities and Challenges

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• Build upon Advanced Hardware:

| Error type | Required ran |
|----------------------------------|---------------------------|
| Beam current variation during | <2% |
| pulse | |
| High frequency ripple in beam | <0.5% |
| current (>1kHz) | |
| Beam current variation from | <2% |
| pulse to pulse | |
| High frequency modulator | <0.02% 0.1% |
| ripple (>1kHz) | |
| Feedforward matching error for | |
| beam loading | 200110 |
| Microphonics induced cavity | <100Hz |
| detuning (including resonant | |
| case) | |
| QL spread (deviation from | <30% |
| optimal value (zero reflection)) | |
| SNR from IQ detection (digital | >75dB |
| domain) | |
| SNR from phase reference | >70dB |
| system (including MO) | |

Opportunities and Challenges

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- It is promising
- Uncertainties in reality.
- Interactive learn from practice(data, experiment)
- Guided by modeling (expressing uncertainty in a precise, quantitative and controlled way)

Learning from Practice: Integrate Data, Modeling and Tests

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Thanks!