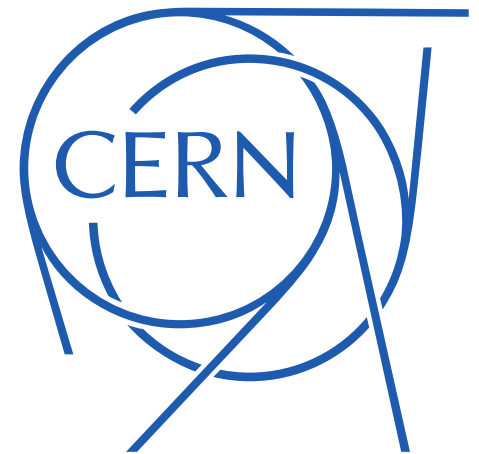


Numerical modeling of fast beam ion instabilities

L. Mether, G. Iadarola, G. Rumolo

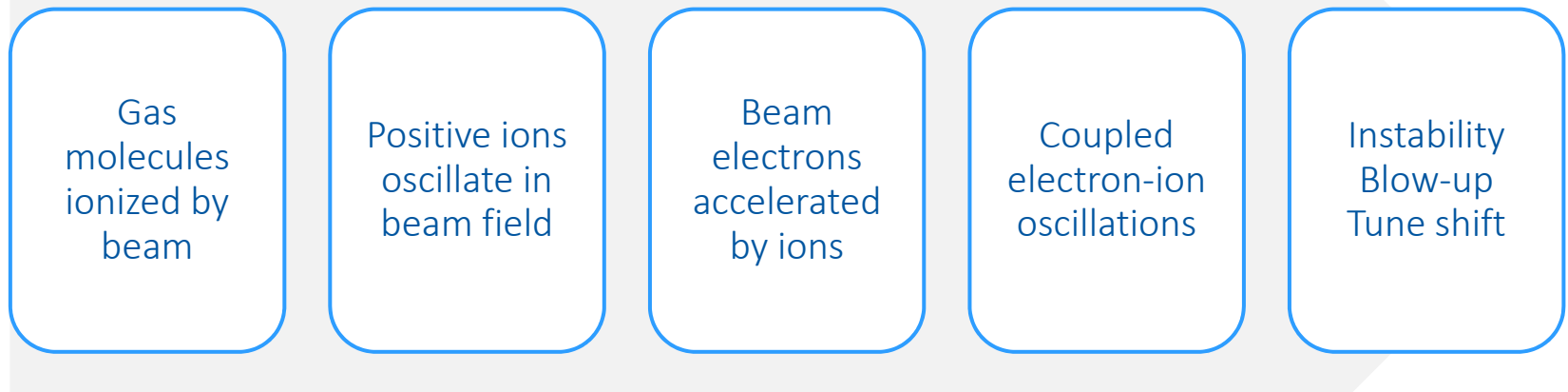
HB2016, 3-8 July, Malmö



Outline

- Introduction
- Simulation outline and tool development
- Application to CLIC main damping ring
- Simulation challenges and prospects
- Summary & outlook

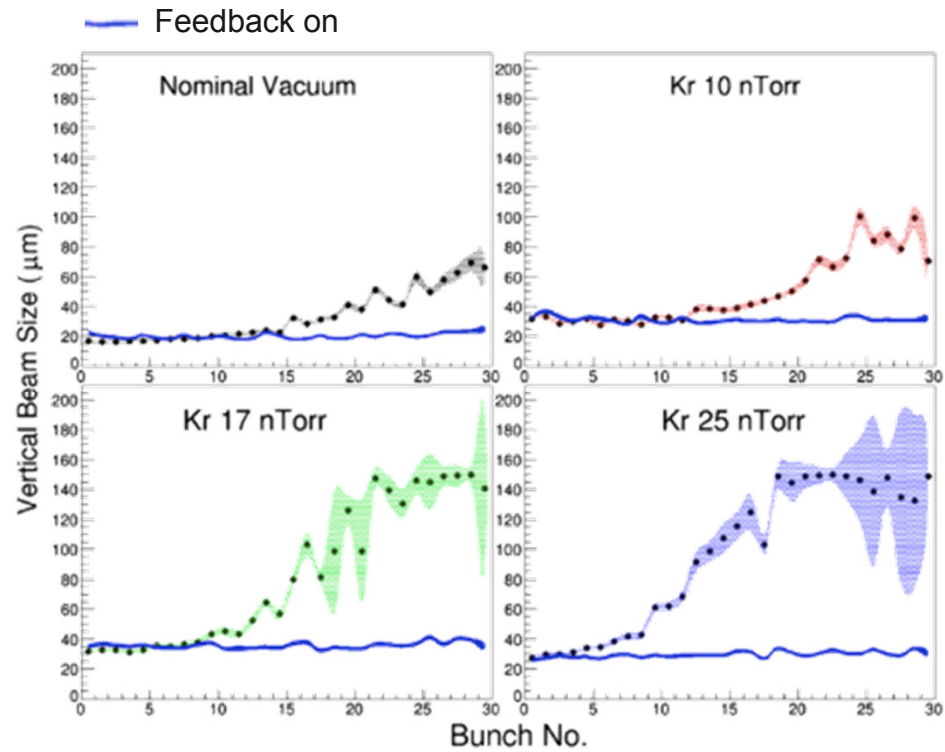
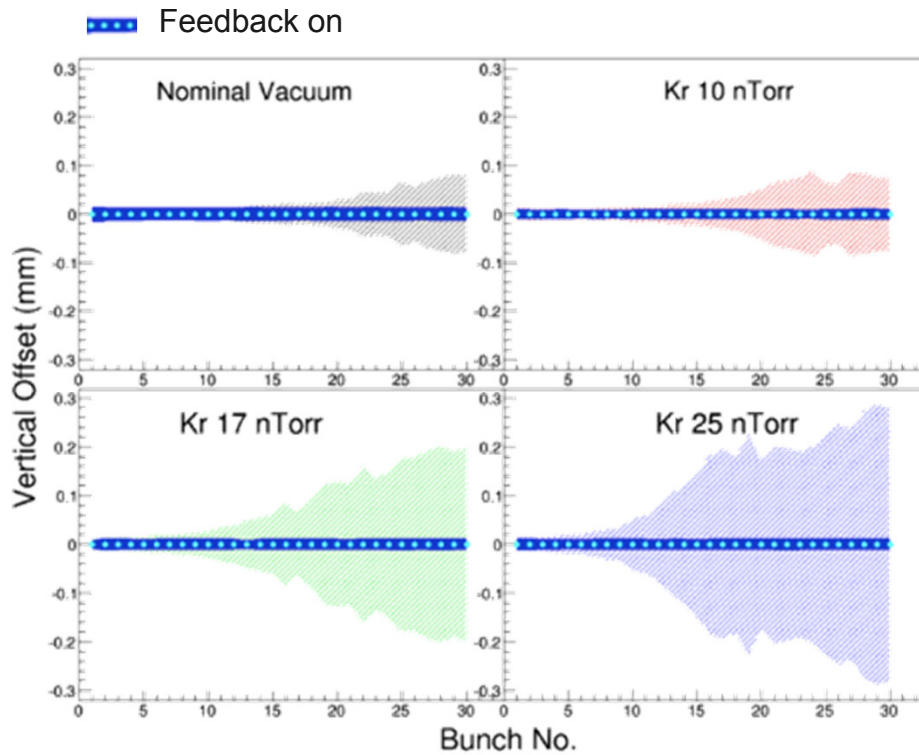
Fast beam ion instability



- For bunch train followed by large gap, ions build up during one train passage
 - Fast beam ion instability (FBII)
- E-cloud-like instability
 - Ion density increases for every bunch passage → effect strongest at tail of train

Observations

- Observed in several machines under vacuum degradation
- Measurements at CESR-TA (Apr 2014)
 - Varying ion species, pressure, bunch charge, train structure, feedback etc.



A. Chatterjee *et al.* Phys. Rev. ST Accel. Beams 18 (2015) 6, 064402

Theory

- Based on linear approximation of Bassetti-Erskine formula
- Dynamics essentially depend on beam brightness
 - Velocity kick for ion with mass number A

$$k_{x,y}(x, y) = \frac{2N_b r_p c}{A} \frac{x, y}{(\sigma_x + \sigma_y) \sigma_{x,y}}$$

- A = ion mass number, N_b = bunch intensity, r_p = classical proton radius

- Trapping condition

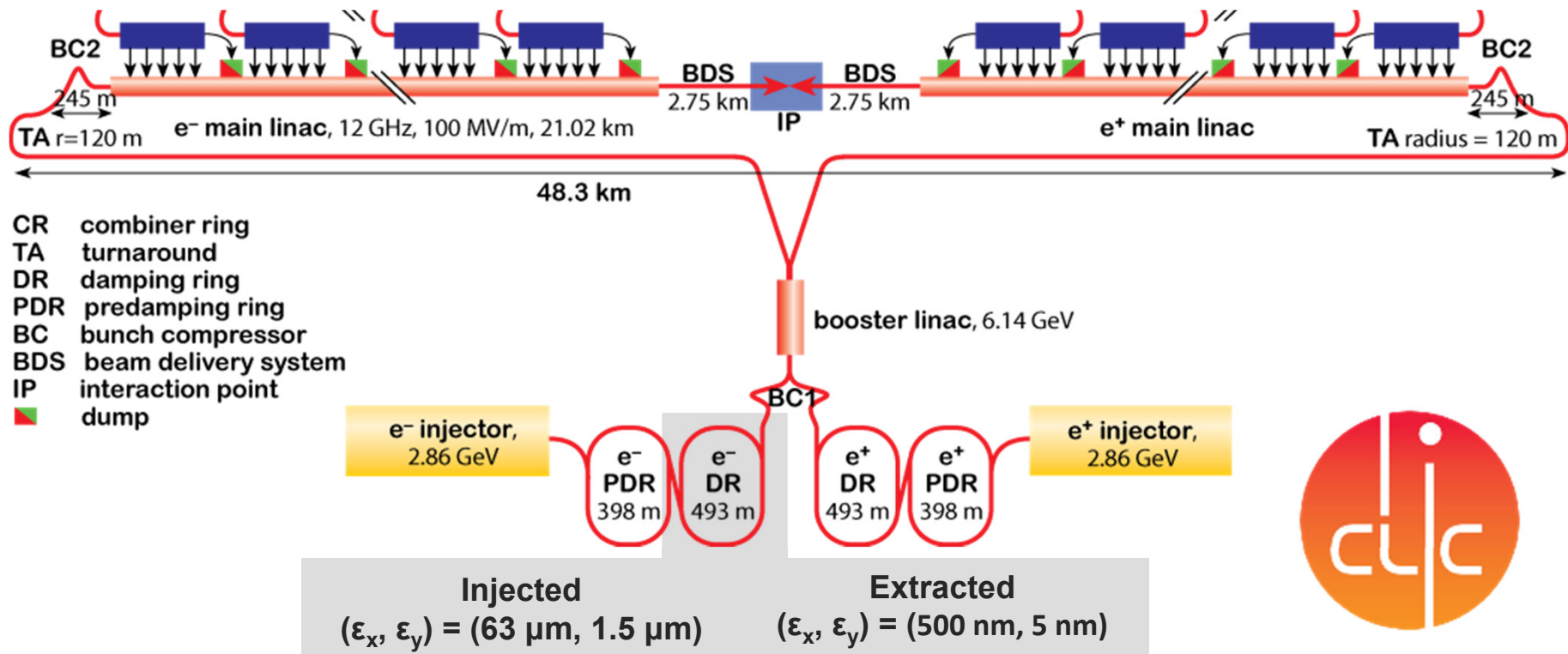
$$A > A_{\text{trap}} = \frac{N_b r_p T_b c}{2(\sigma_x + \sigma_y) \sigma_{x,y}}$$

- T_b = bunch spacing

Fast beam-ion instability. I. Linear theory and simulations
Raubenheimer *et al.* Phys. Rev. E 52, 5, 5487

CLIC accelerator complex

Parameters	Value
Bunch population	4×10^9
Bunches per train	312
Bunch spacing [ns]	0.5
Bunch length (rms) [mm]	1.6



Simulation studies

- Aim to estimate vacuum (and/or feedback) requirements imposed by FBII
- Simulated with strong-strong 2D macroparticle multi-bunch tracking code

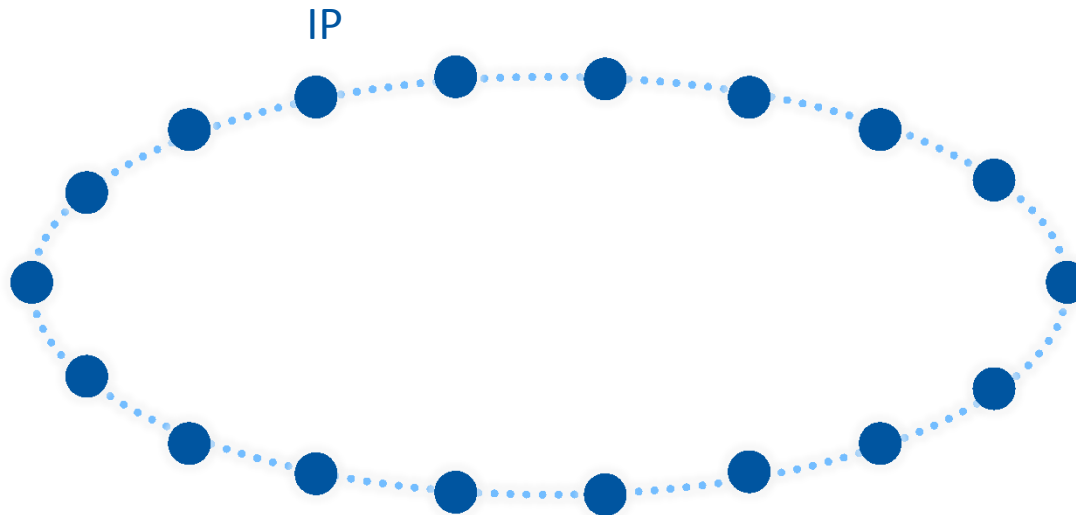
- FASTION
 - Developed and used for studies of FBII in linear CLIC structures
 - Based on HEADTAIL for e-cloud
 - Development required to adapt to damping rings

- Several CERN beam dynamics codes re-designed recently
 - Electron cloud build-up: ELOUD → PyELOUD
 - Collective effects: HEADTAIL → PyHEADTAIL
 - Aim to make codes more maintainable, flexible and user friendly

- Decision to incorporate FASTION functionality into PyELOUD – PyHEADTAIL

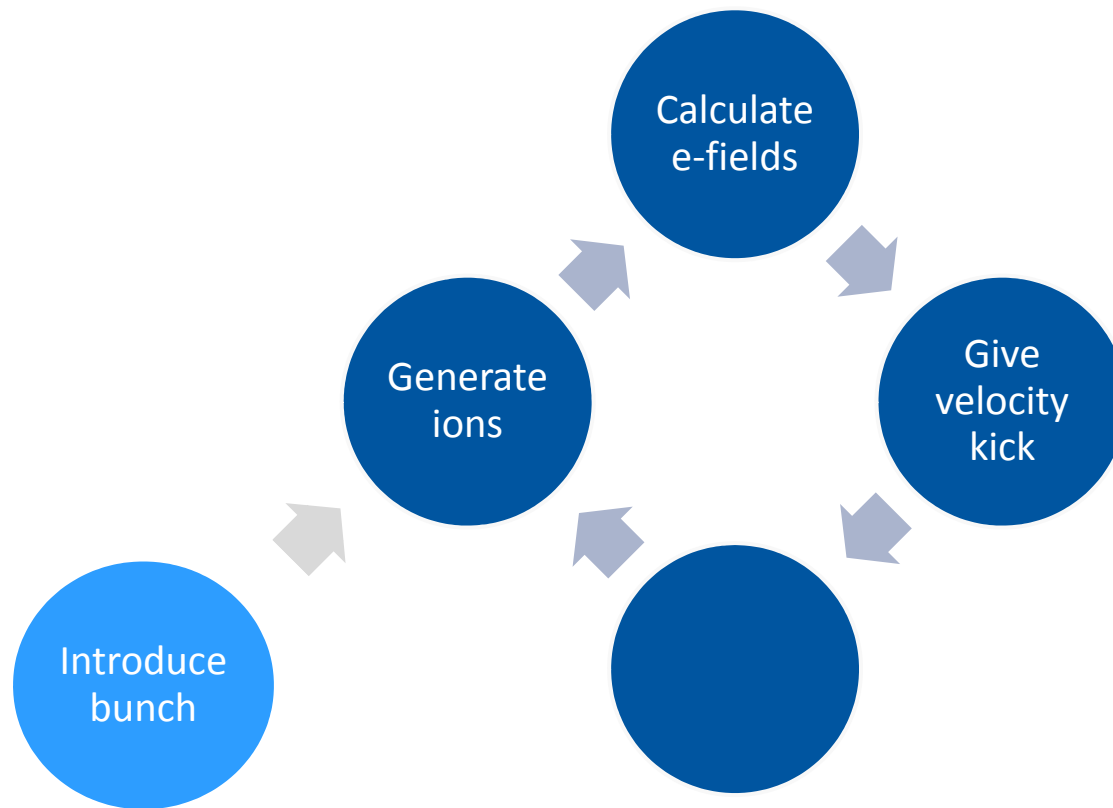
Simulation outline

- The machine lattice is divided into a number of interaction points (IP)
 - An electron bunch train is tracked through the lattice
 - In every IP, the beam-ion interaction is simulated



Simulation outline

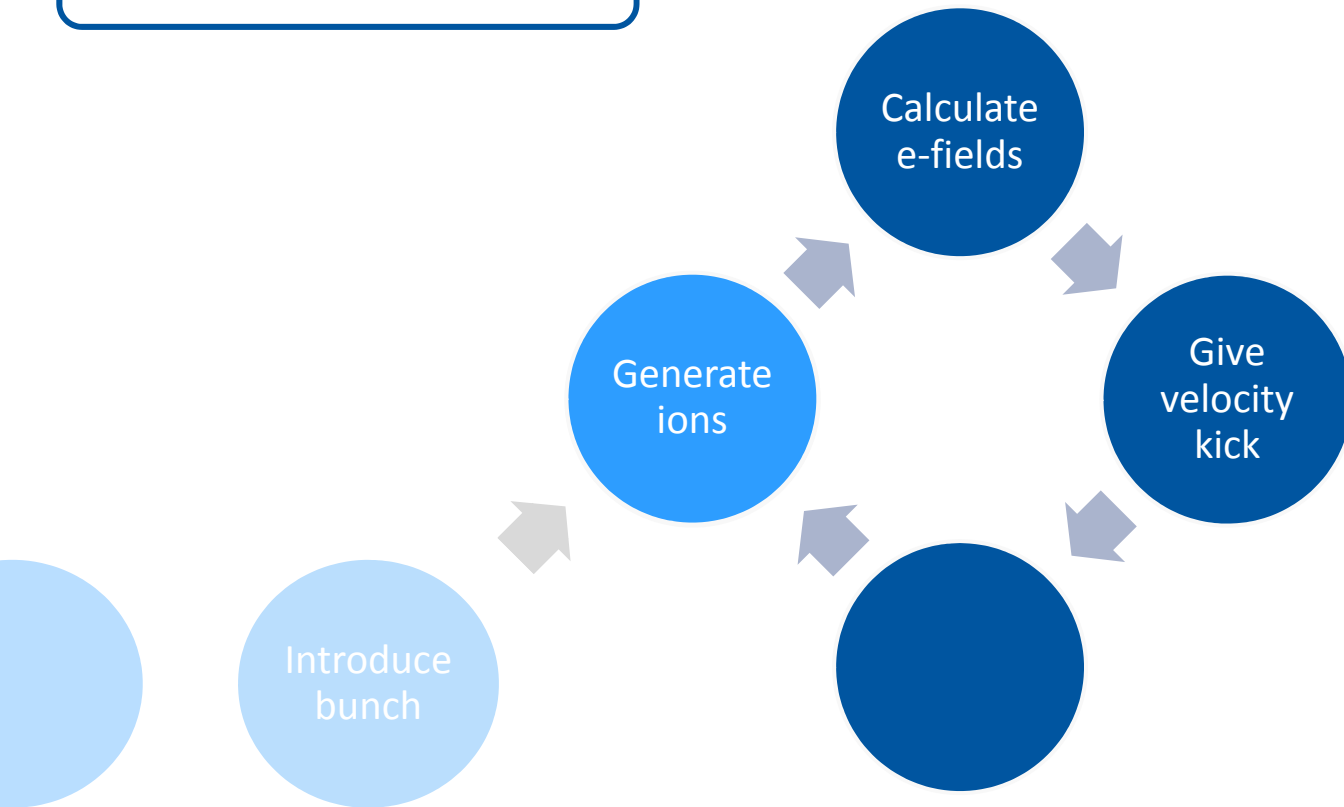
- In every interaction point, the beam is passed bunch by bunch



Simulation outline

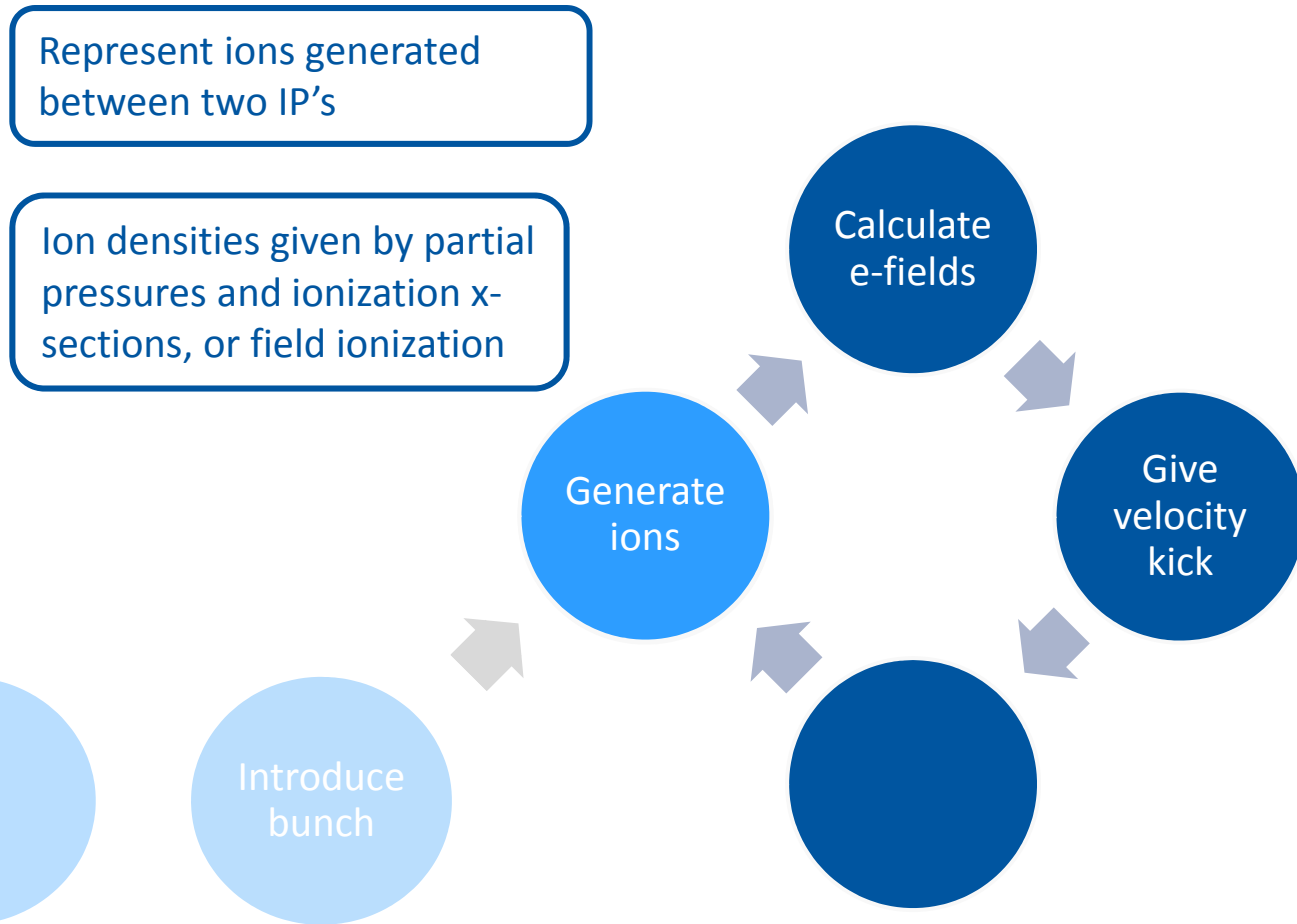
- In every interaction point, the beam is passed bunch by bunch

Represent ions generated
between two IP's



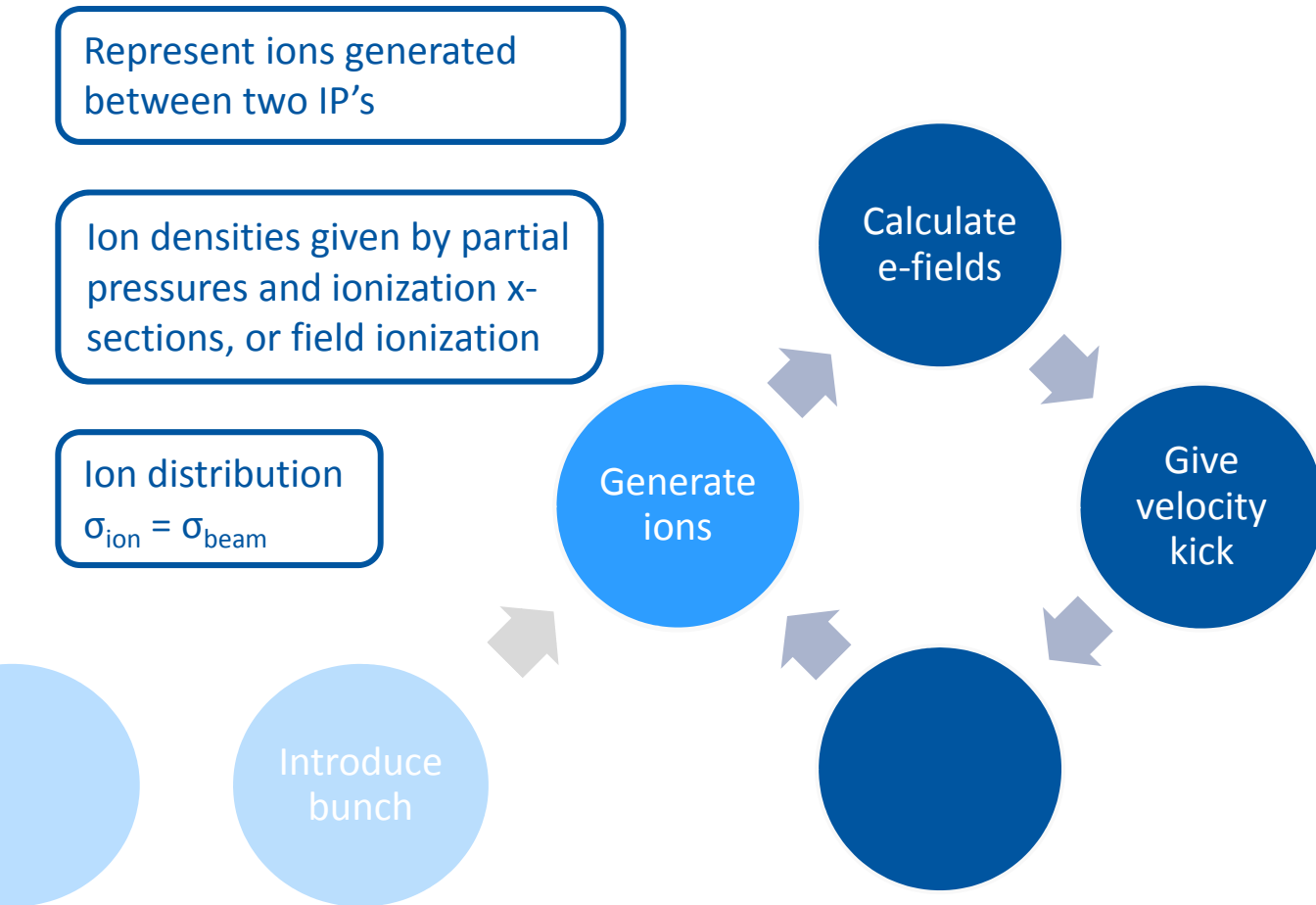
Simulation outline

- In every interaction point, the beam is passed bunch by bunch



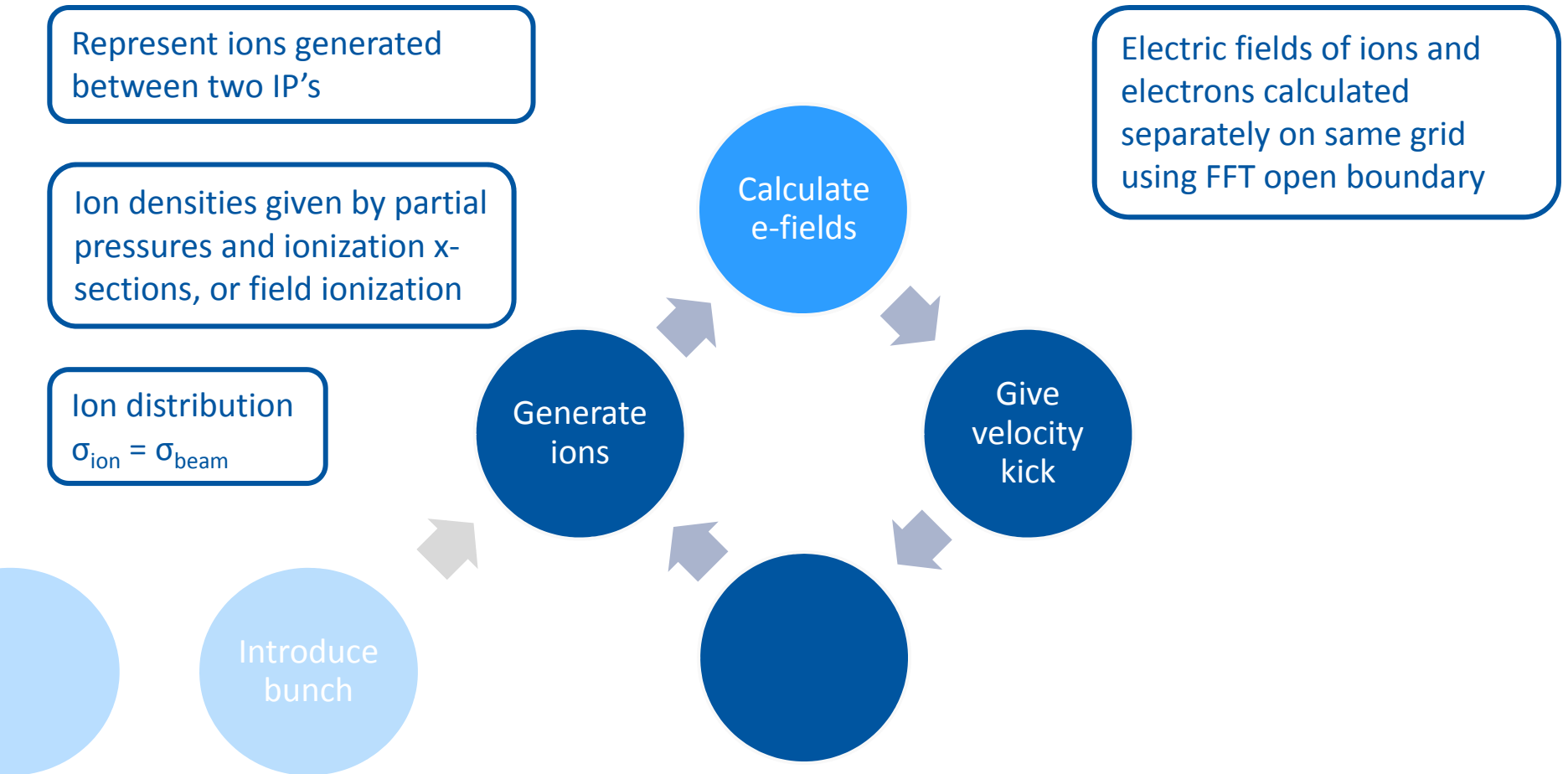
Simulation outline

- In every interaction point, the beam is passed bunch by bunch



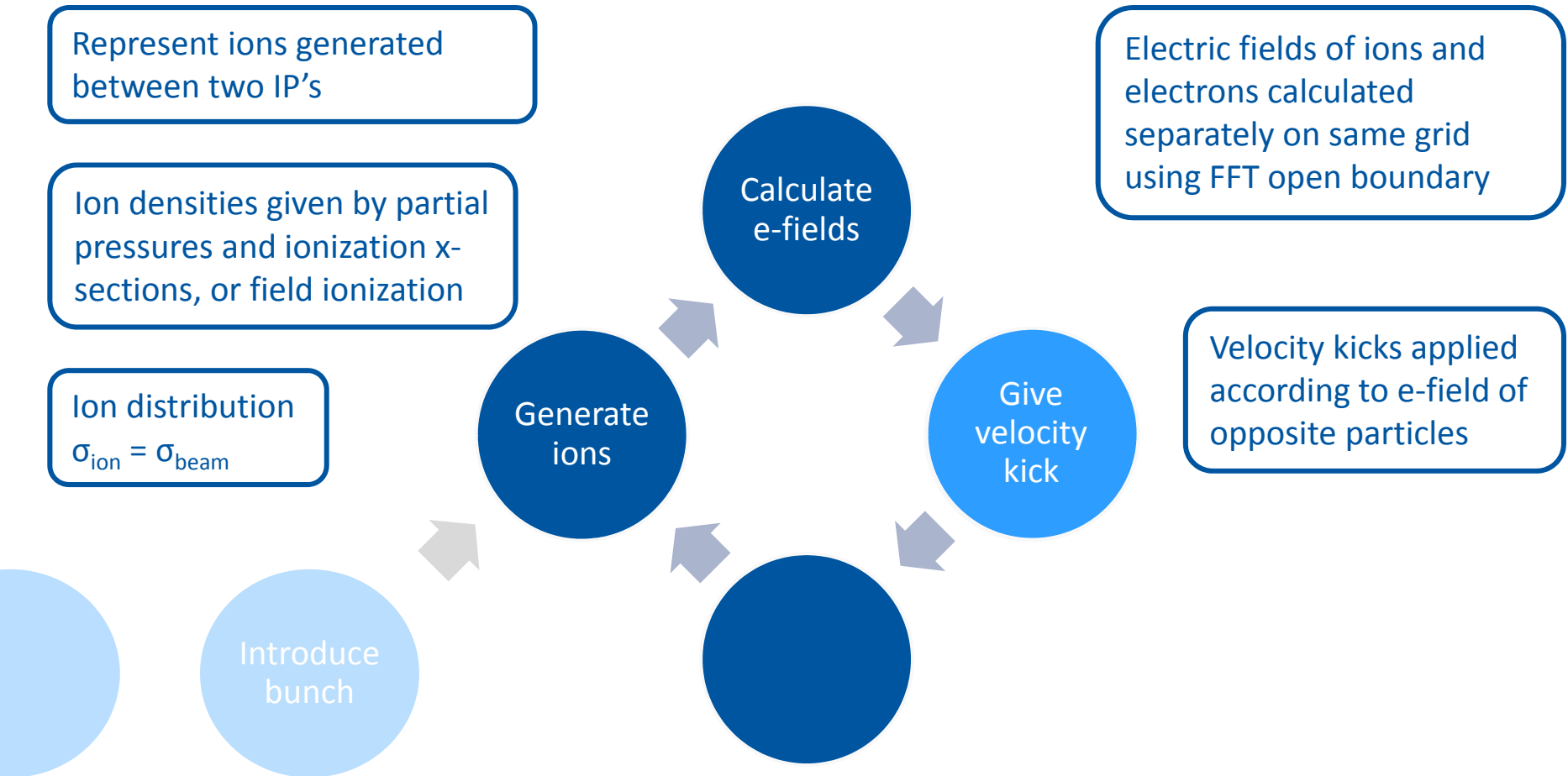
Simulation outline

- In every interaction point, the beam is passed bunch by bunch



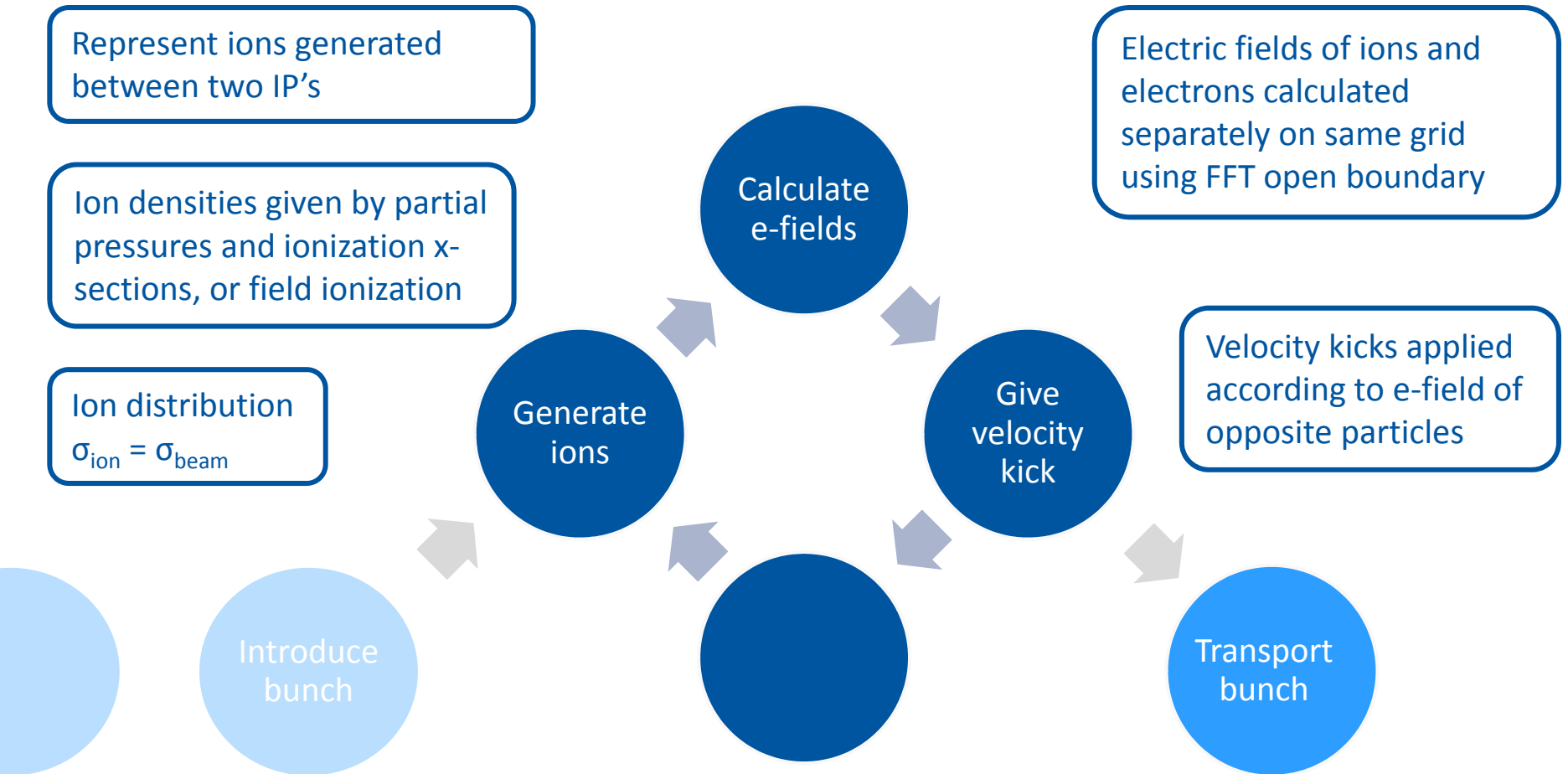
Simulation outline

- In every interaction point, the beam is passed bunch by bunch



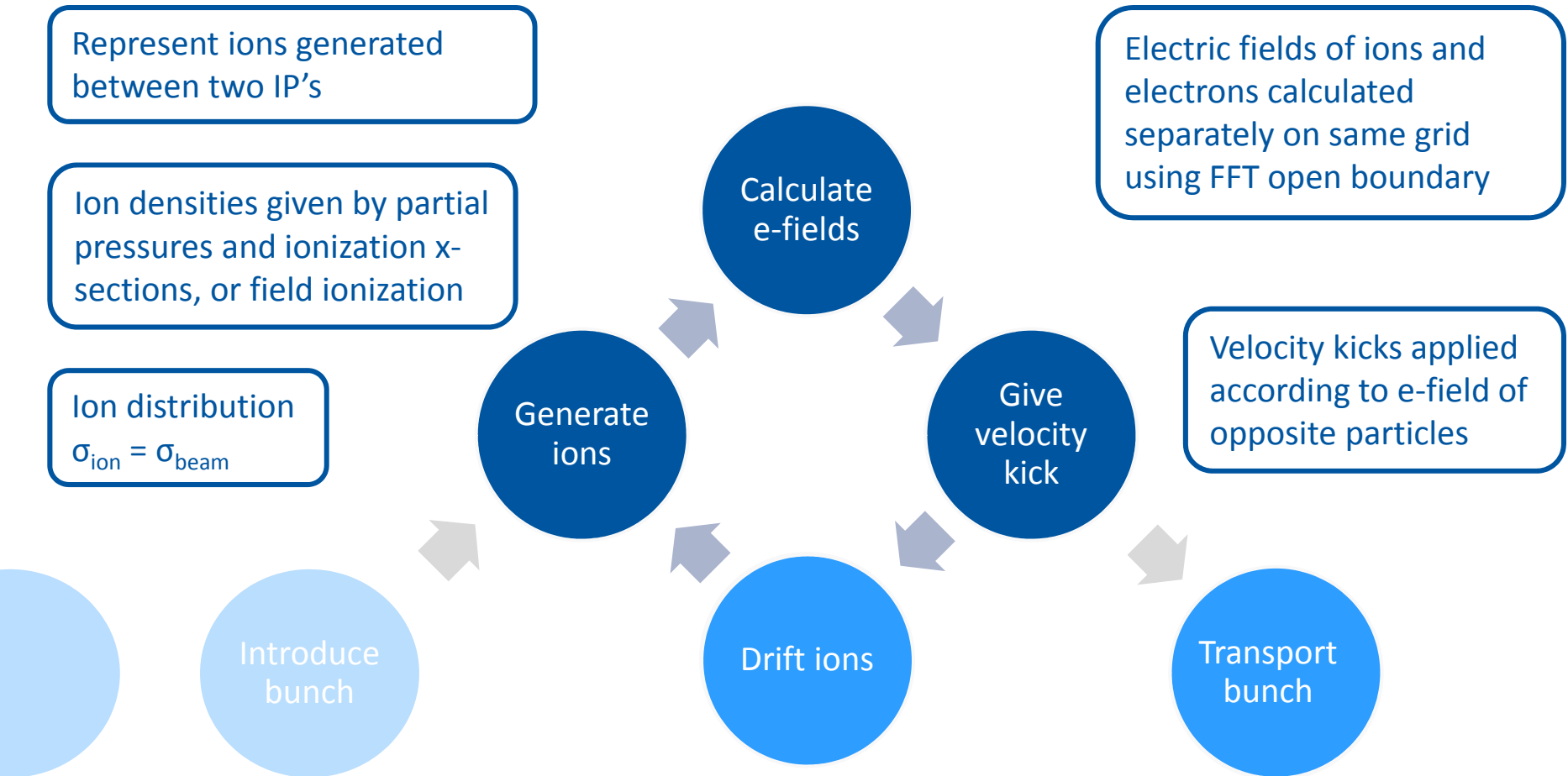
Simulation outline

- In every interaction point, the beam is passed bunch by bunch



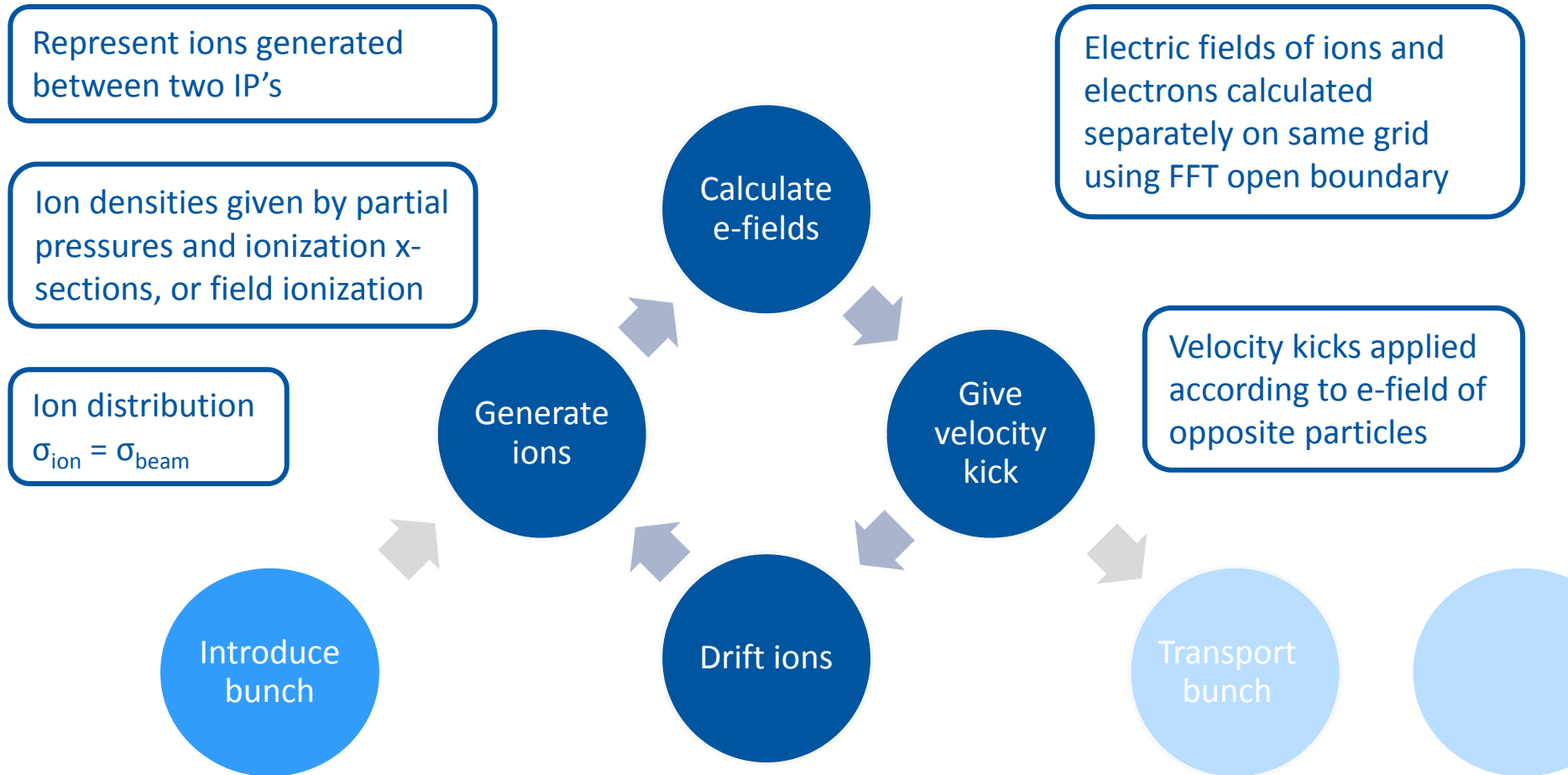
Simulation outline

- In every interaction point, the beam is passed bunch by bunch



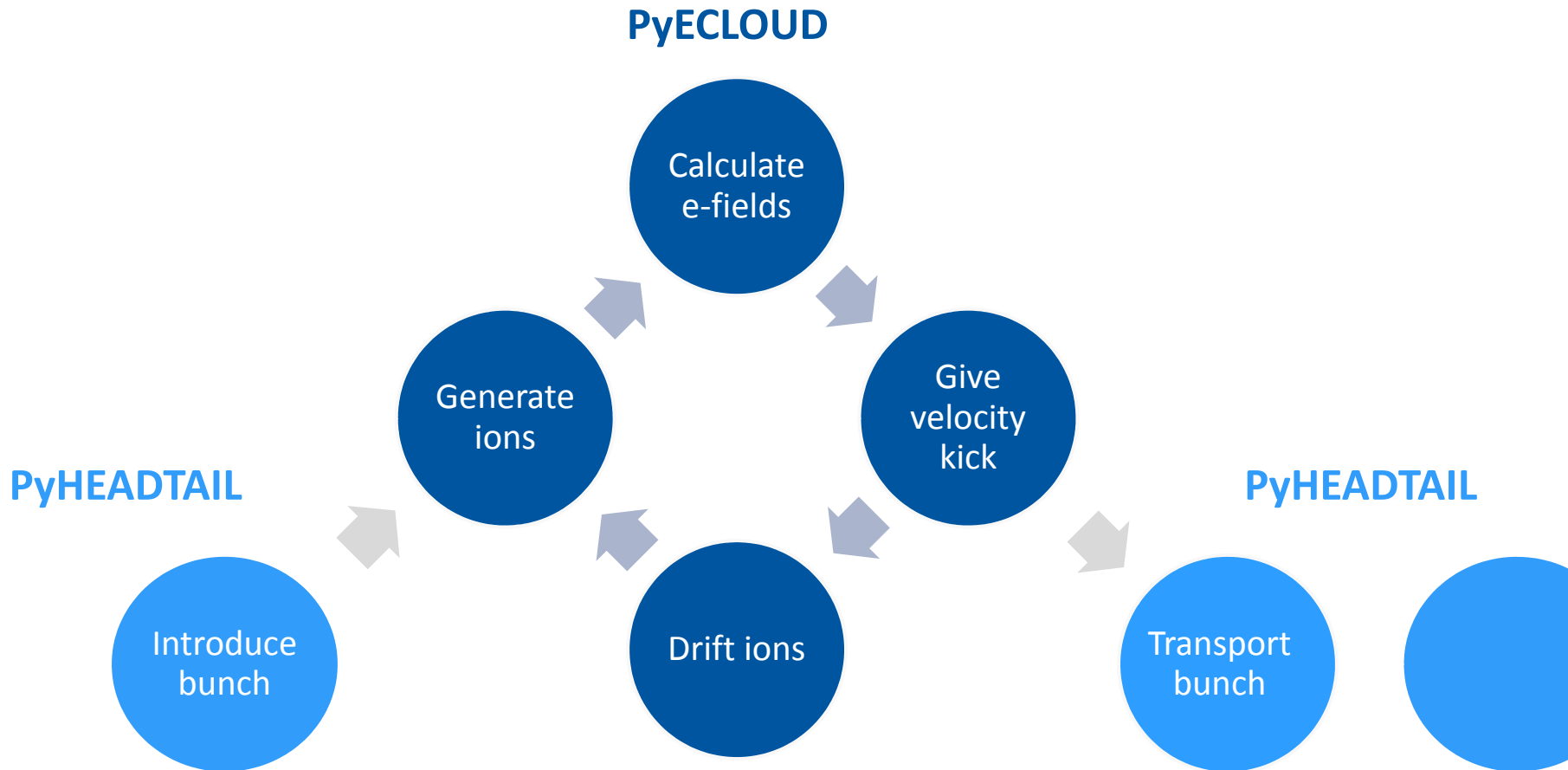
Simulation outline

- In every interaction point, the beam is passed bunch by bunch



Simulation outline

- Implementation in PyECLOUD and PyHEADTAIL



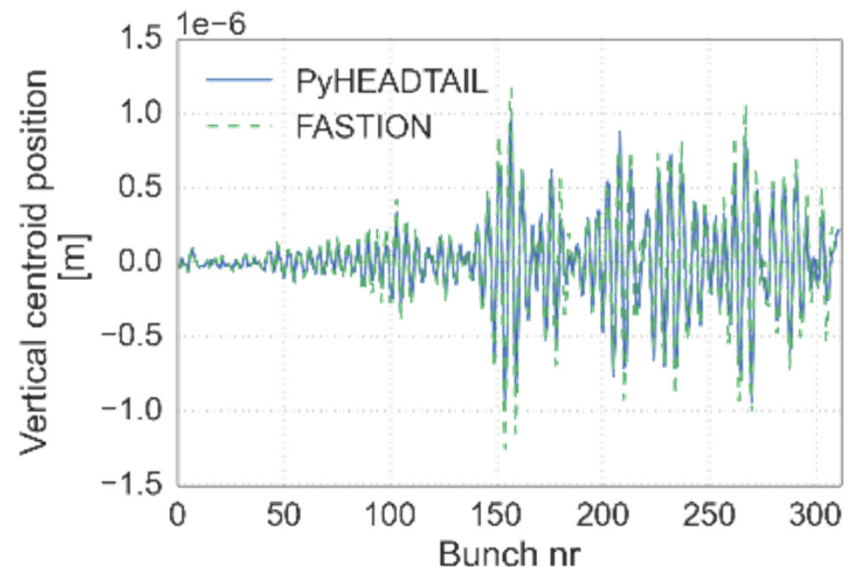
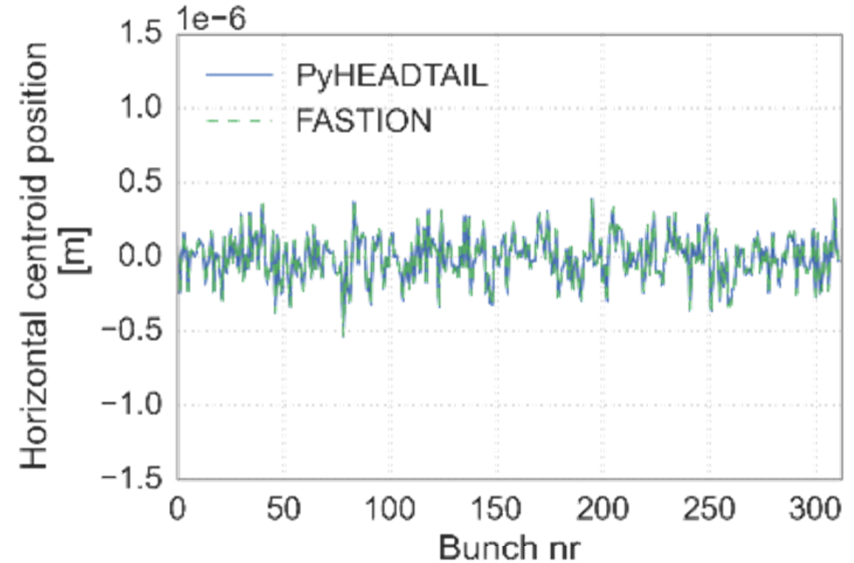
Implementation

- Generalization to arbitrary charge and mass in PyECLOUD and PyHEADTAIL
- Extension of PyECLOUD gas ionization routines
 - Multiple ion species, field ionization
- Ion boundary conditions (perfect absorber)
- Modification of PyPIC FFT solver method
 - Rectangular (non-square) grid cells, useful due to the very flat beams
- Single kick interaction
- Implementation of multi-bunch in PyHEADTAIL
 - Create and track multi-bunch beam, “slice” into bunches for interaction

Application to CLIC damping ring

- Benchmark study I
 - Bunch train initialized identically in FASTION and PyEC-PyHT
 - Machine lattice divided in 677 interaction points ~ 60 cm long
 - Residual gas: water, $A = 18$
 - Pressure 20 nTorr
- Track over 1 turn

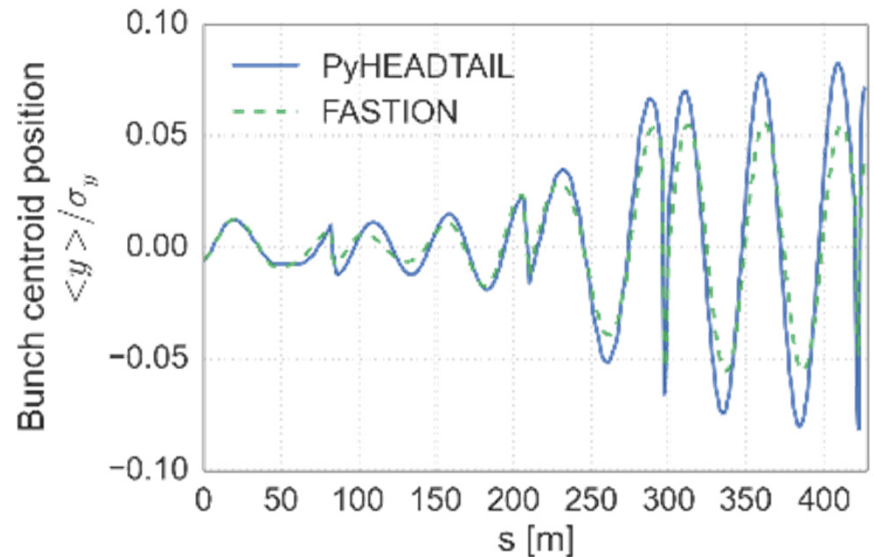
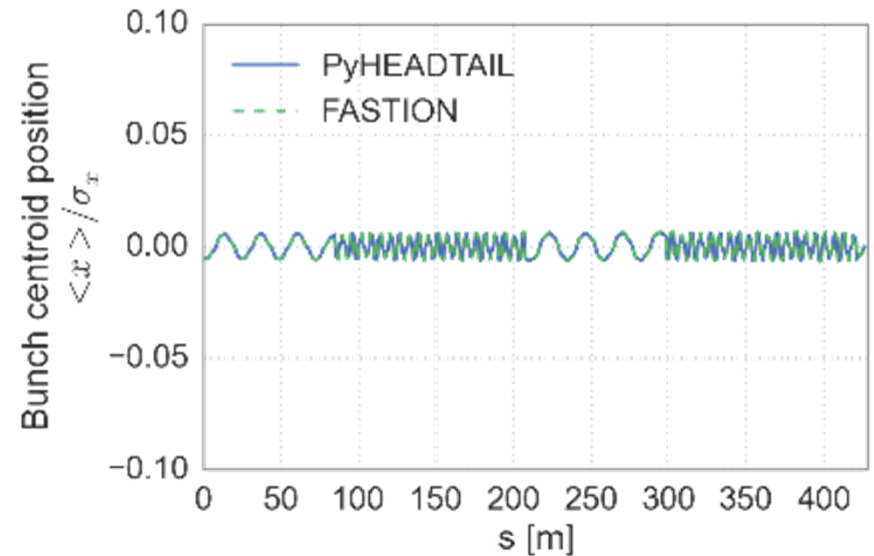
- Bunch train centroids after 1 turn
- Unstable motion in vertical plane, as expected



Application to CLIC damping ring

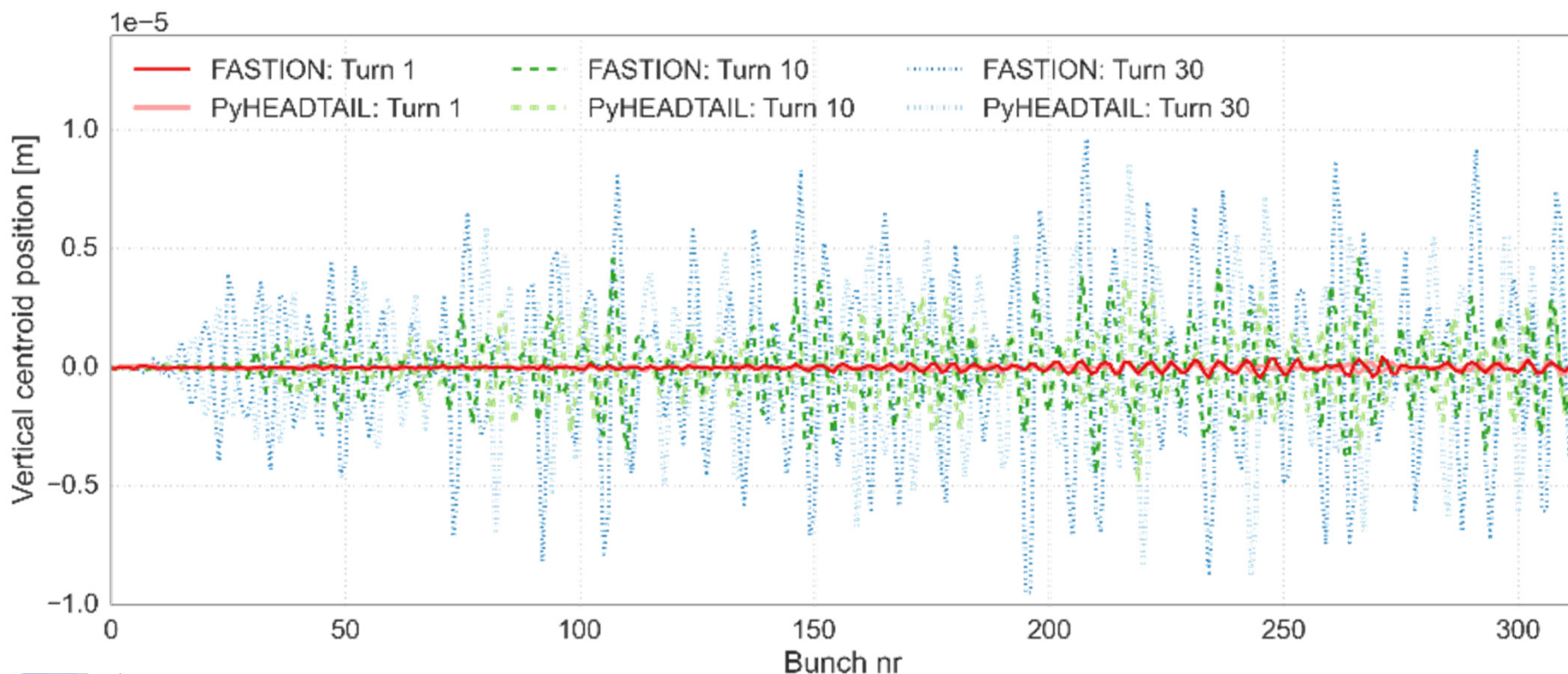
- Benchmark study I
 - Bunch train initialized identically in FASTION and PyEC-PyHT
 - Machine lattice divided in 677 interaction points ~ 60 cm long
 - Residual gas: water, $A = 18$
 - Pressure 20 nTorr
- Track over 1 turn

- Centroid of last bunch along turn
- Good agreement between FASTION and PyECLOUD-PyHEADTAIL



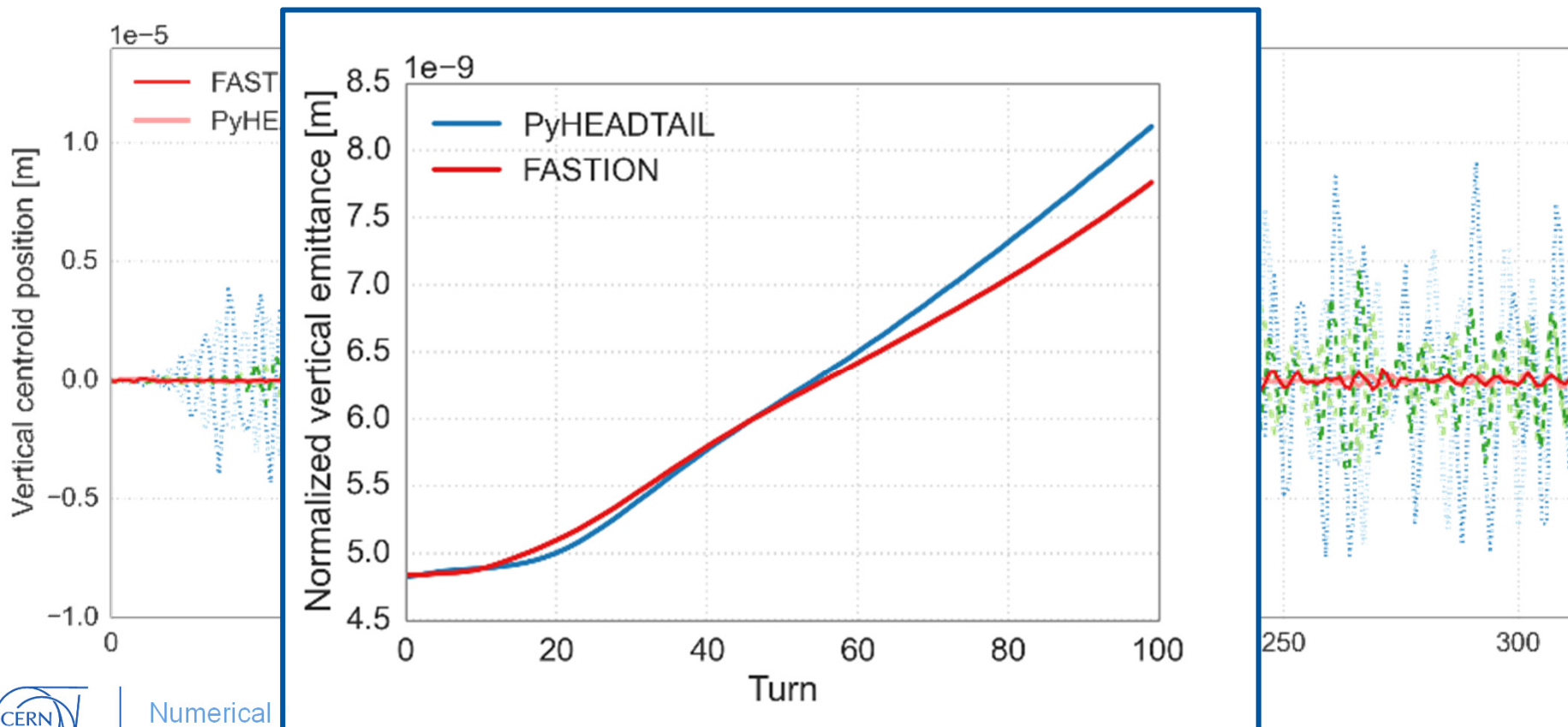
Application to CLIC damping ring

- Benchmark study II
 - Bunch train initialized with different random seeds in FASTION and PyEC-PyHT
 - Residual gas: water, $A = 18$, $P = 10$ nTorr
- Track over 100 turn, snapshots of train after 1, 10 and 30 turns



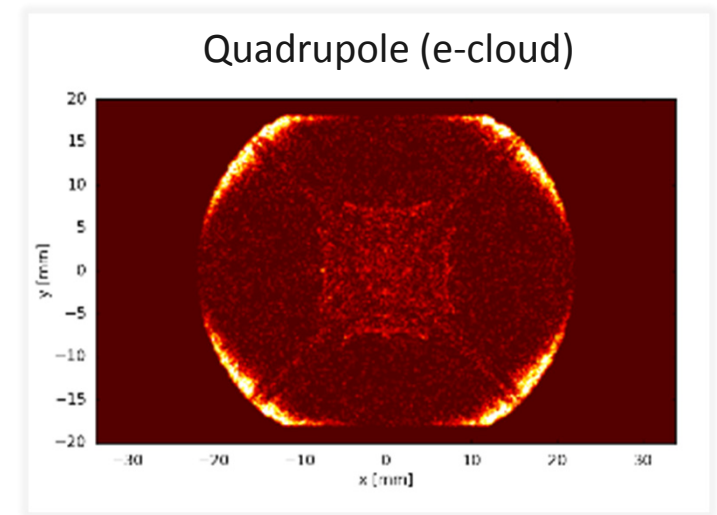
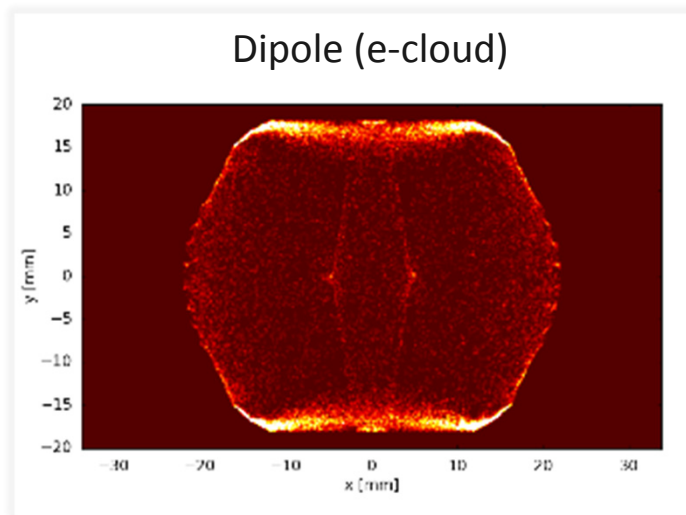
Application to CLIC damping ring

- Benchmark study II
 - Bunch train initialized with different random seeds in FASTION and PyEC-PyHT
 - Residual gas: water, $A = 18$, $P = 10$ nTorr
- Track over 100 turn, vertical emittance growth of last bunch



Simulation tool status

- Basic simulation scenario agrees with FASTION
- Ready to test new features available in PyECLOUD and PyHEADTAIL
 - Ion self space charge
 - PIC solvers with boundary for complex beam chamber profiles
 - Dipole and quadrupole magnetic fields on ion motion
 - Bunch slices
 - Synchrotron motion, chromaticity, transverse feedback



Challenges

➤ Resolution

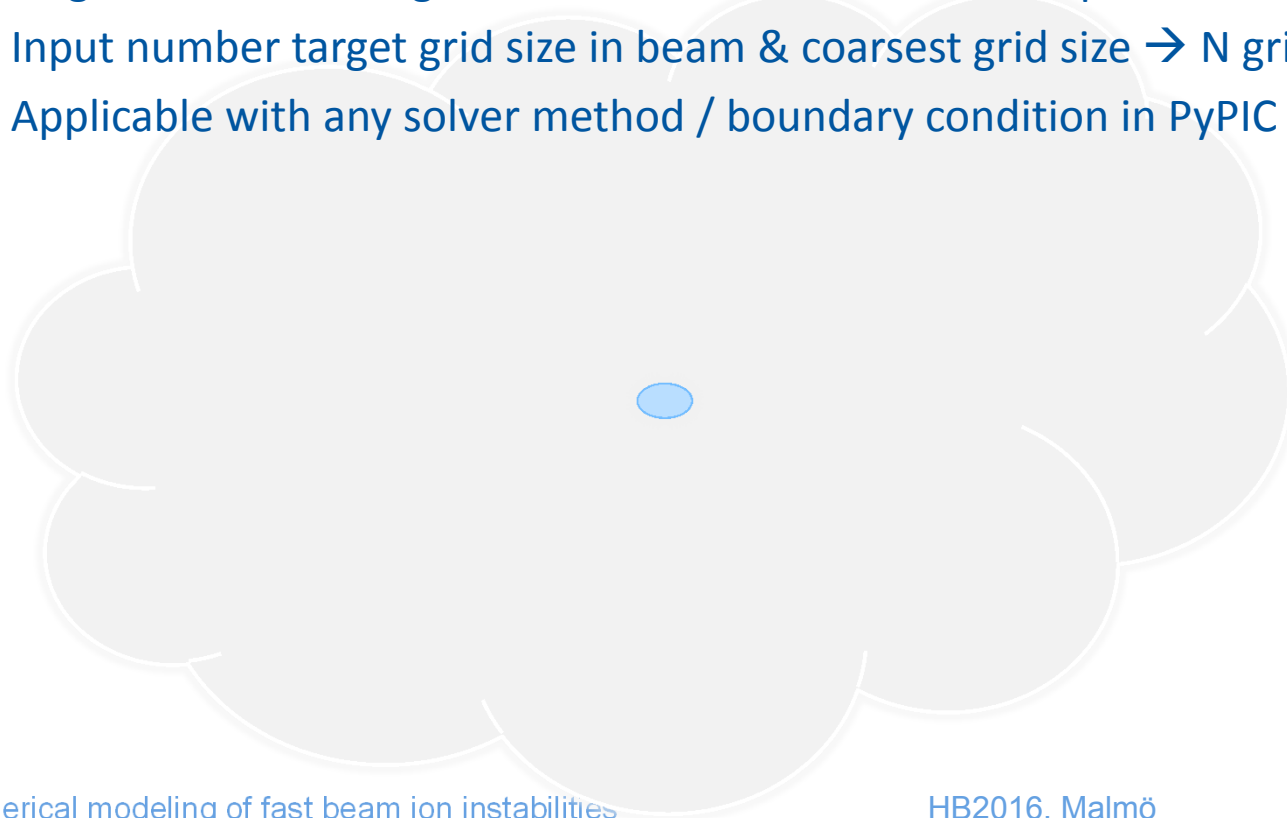
- Simulating two-stream instabilities generally challenging: big cloud – small beam
- Especially for lepton machines, with tiny beams
- For FBII, variations in electric field at slightly different locations inside beam are an important ingredient in exciting the instability
- Simply increasing the number of PIC grid cells quickly leads to unacceptably long execution times, and eventually memory issues



Challenges

➤ Resolution

- Solution: multiple nested grids
- Dual-grid method with fine grid around beam, coarse grid for cloud in FASTION
- Multigrid method, using modular structure, under development in PyPIC
 - Input number target grid size in beam & coarsest grid size → N grids
 - Applicable with any solver method / boundary condition in PyPIC



➤ Example

- Compare single grid vs. multigrid with 3 grids
- Reference from Bassetti-Erskine
- Similar execution times
- Circular beam

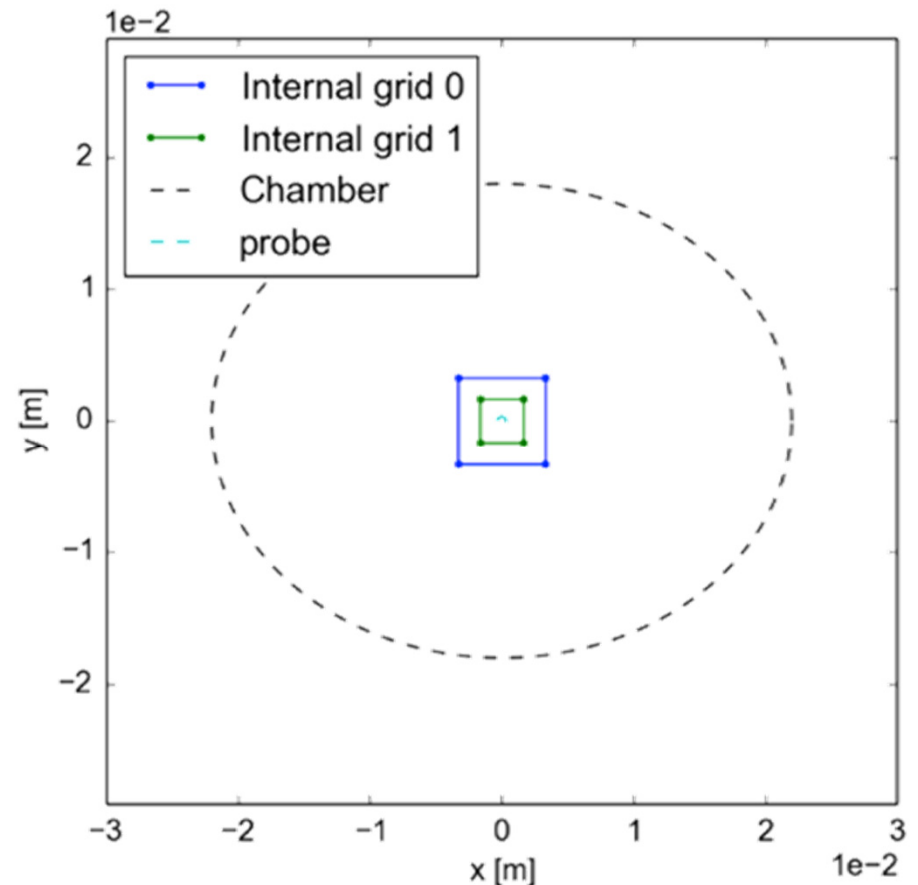
$$\sigma_x = 3.30e-04 \text{ [m]}$$

$$\sigma_y = 3.30e-04 \text{ [m]}$$

$$\Delta h_{single} = 3.95e-04 \text{ [m]}$$

$$\Delta h_{multi} = 1.32e-04 \text{ [m]}$$

$$\Delta h_{BE} = 9.89e-05 \text{ [m]}$$

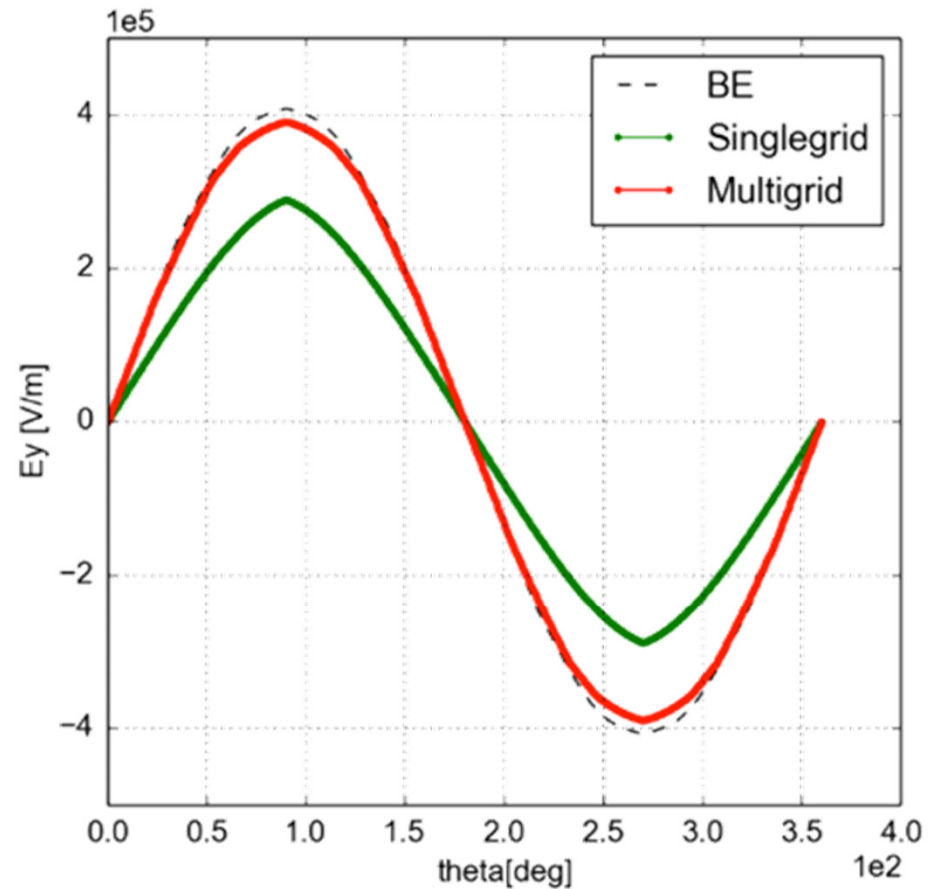
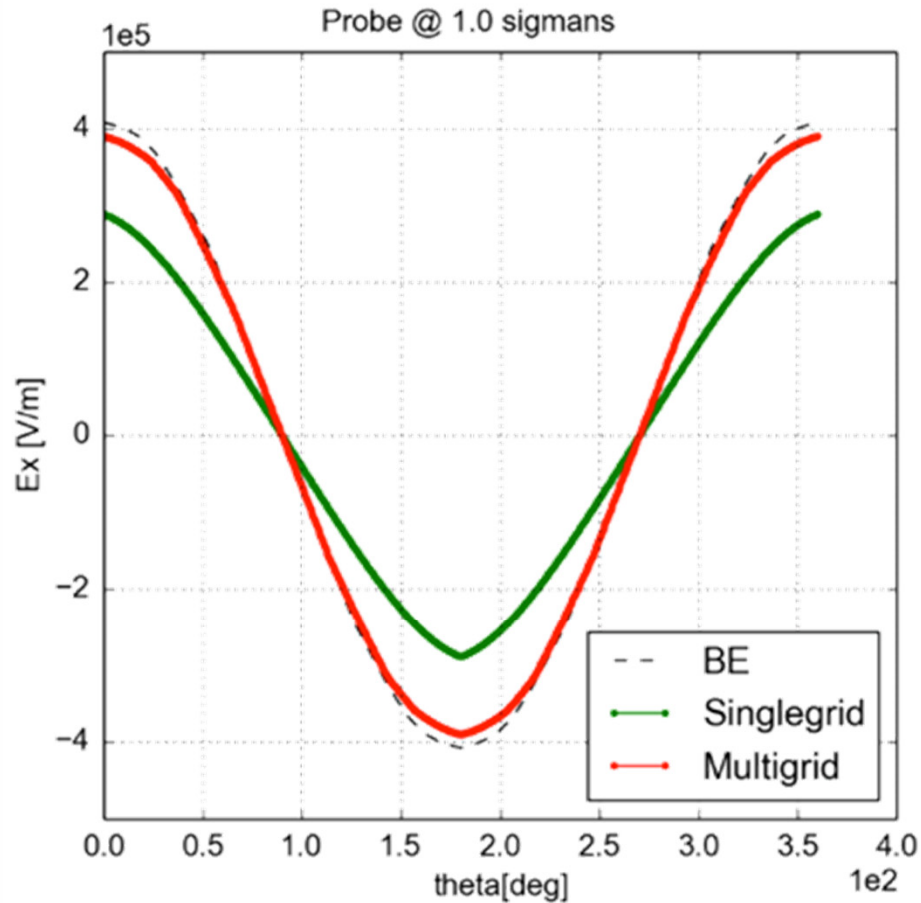


Multigrid method

with E. Belli

➤ Example

- Electric fields at 1 sigma

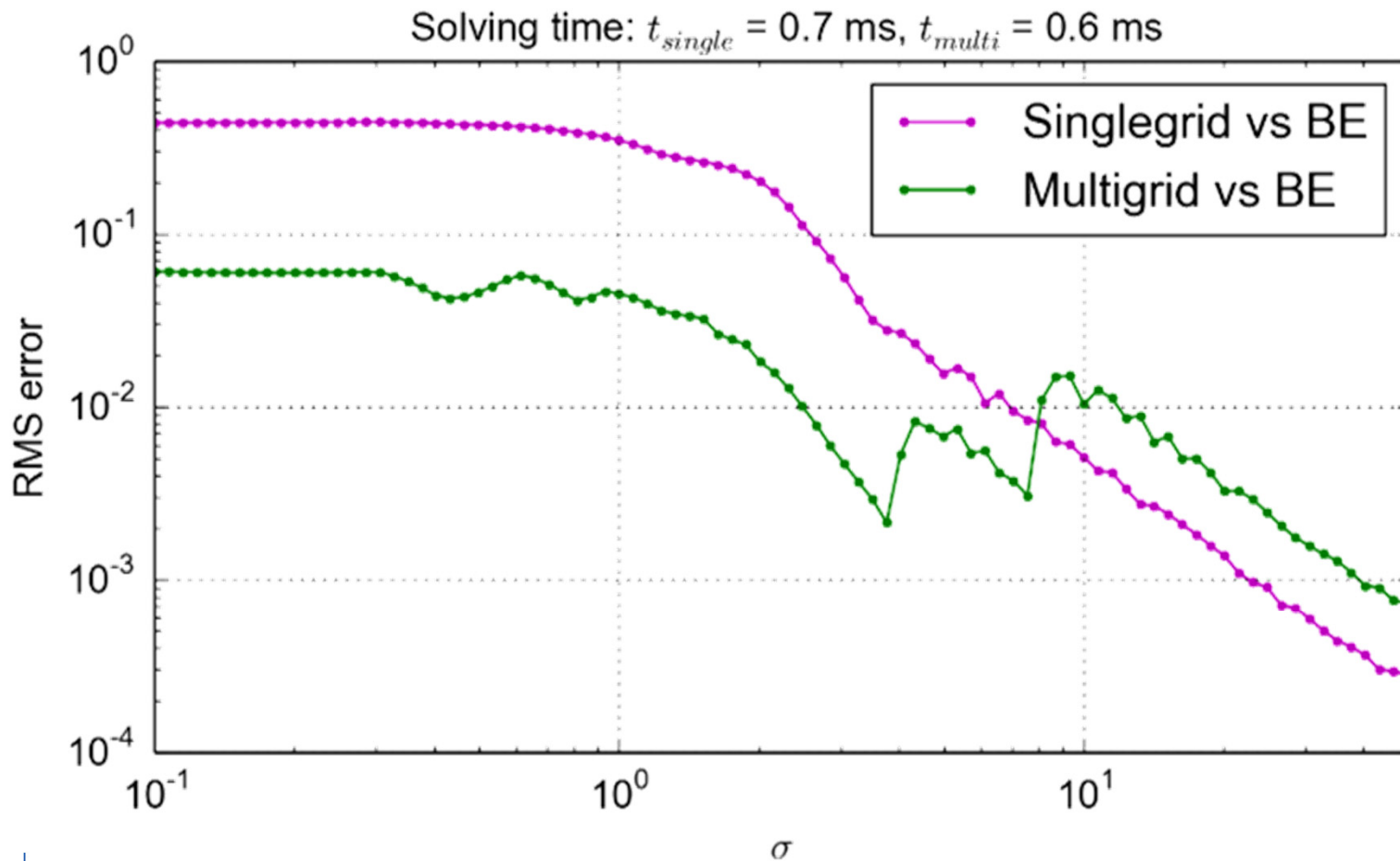


Multigrid method

with E. Belli

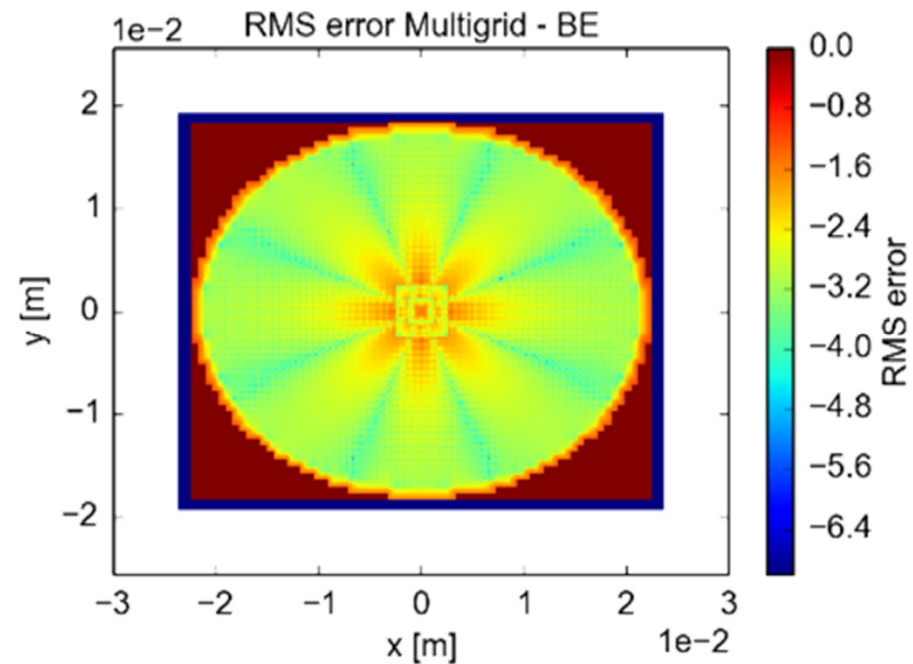
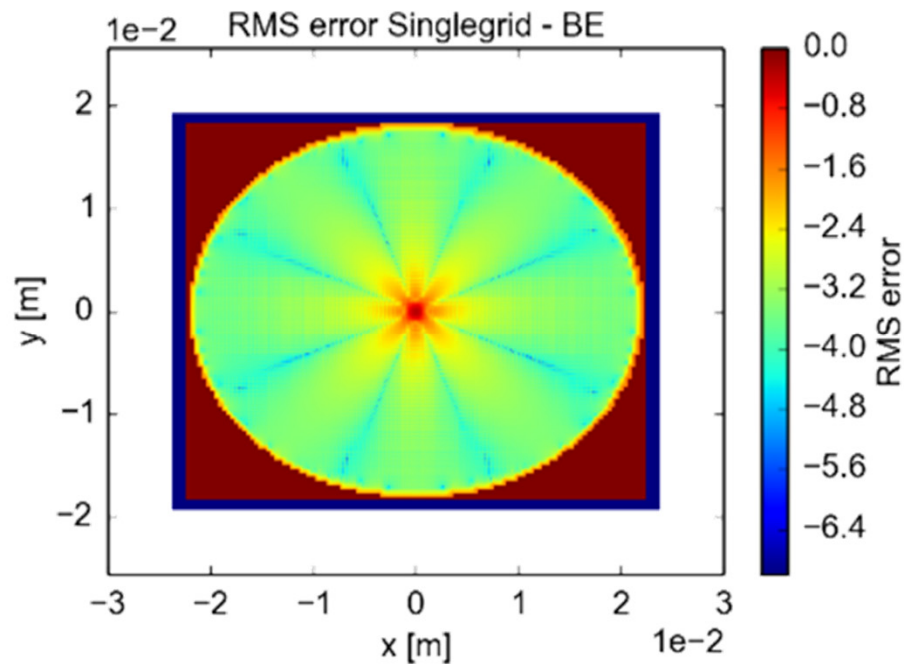
➤ Example

- RMS error compared to Bassetti-Erskine



➤ Example

- RMS error map (logarithmic scale)
- Better resolution around beam in multigrid
- At the expense of slightly lower resolution outside (for similar run times)



Challenges

➤ Run-time performance

- Dynamics of instability proportional to beam brightness
- In damping ring, brightness increases by large factor during damping period
- To capture full dynamics, ideally simulate full damping period
 - CLIC main damping ring, damping time around 2 ms ~ 1400 turns
- FASTION: 1 turn ~ 20 min → 20 days for full damping cycle
- PyEC-PyHT: currently ~ 50 % slower
 - Profiling shows is largely due to FFT solver, room for optimization
 - Multigrid may also help
- Too long in both cases!

➤ Effort ongoing to create parallelization layer applicable to ion, e-cloud & other studies

Summary & outlook

- Fast beam ion instability modeling implemented in PyECLOUD – PyHEADTAIL
 - First application to CLIC main damping ring
 - Benchmarked against FASTION
 - Ready for systematic studies
- Many new features available
 - Future studies to estimate effect on instability
- Multigrid solver methods have been implemented
 - Essential for good resolution without compromising on performance
 - First full multigrid simulations with PyEC-PyHT are being run
- Long run times still a problem
 - Parallelization effort ongoing

Thank you!

Thanks to PyPIC, PyECLOUD and PyHEADTAIL developers:
H. Bartosik, E. Belli, S. Hegglin, K.Li, A. Oeftiger,
A. Passarelli, A. Romano, M. Schenk

